

## ${\bf JAWAHARLAL\ NEHRUTECHNOLOGICALUNIVERSITY:} {\bf KAKINADA}$

#### KAKINADA-533003, Andhra Pradesh, India

R-16 Syllabus for ECE.JNTUK

I Year-I Semester		L	T	P	C
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	MATHEMATICS – I (R161102)				

**Prerequisite Course:** Knowledge and application of differentiation and integration

## **Course Description and Objectives:**

- 1. The course is designed to equip the students with the necessary mathematical skills and techniques that are essential for an engineering course.
- 2. The skills derived from the course will help the student from a necessary base to develop analytic and design concepts.

## **Course Outcomes:**

Upon completion of the course, the student will be able to achieve the following outcomes.

CO	Course Outcomes	
1	Solve linear differential equations of first order.	
2	Solve linear differential equations of second and higher order.	
3	Determine Laplace transform and inverse Laplace transform of various functions	
4	Calculate total derivative, Jocobian and exreme values of functions of two	3
	variables.	
5	Solve partial differential equations of first order.	4
6	Solve partial differential equations of second and higher order.	4

#### **Syllabus:**

## **UNIT I:**

#### Differential equations of first order and first degree:

Linear-Bernoulli-Exact-Reducible to exact. Applications: Newton's Law of cooling-Law of natural growth and decay-Orthogonal trajectories- Electrical circuits- Chemical reactions.

#### **UNIT II:**

## Linear differential equations of higher order:

Non-homogeneous equations of higher order with constant coefficients with RHS term of the type  $e^{ax}$ , sin ax, cos ax, polynomials in x,  $e^{ax}$  V(x), xV(x)- Method of Variation of parameters. Applications: LCR circuit, Simple Harmonic motion.

#### **UNIT III:**

#### **Laplace transforms:**

Laplace transforms of standard functions-Shifting theorems - Transforms of derivatives and integrals - Unit step function -Dirac's delta function- Inverse Laplace transforms- Convolution theorem (with out proof). Applications: Solving ordinary differential equations (initial value problems) using Laplace transforms.

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#### **UNIT IV:**

#### Partial differentiation:

Introduction- Homogeneous function-Euler's theorem-Total derivative-Chain rule-Generalized Mean value theorem for single variable (without proof)-Taylor's and Mc Laurent's series expansion of functions of two variables—Functional dependence- Jacobian. Applications: Maxima and Minima of functions of two variables without constraints and Lagrange's method (with constraints).

#### **UNIT V:**

## First order Partial differential equations:

Formation of partial differential equations by elimination of arbitrary constants and arbitrary functions –solutions of first order linear (Lagrange) equation and nonlinear (standard types) equations.

#### **UNIT VI:**

### **Higher order Partial differential equations:**

Solutions of Linear Partial differential equations with constant coefficients. RHS term of the type  $e^{ax+by}$ ,  $\sin(ax+by)$ ,  $\cos(ax+by)$ ,  $x^m y^n$ . Classification of second order partial differential equations.

#### **TEXT BOOKS:**

- 1. B.S.Grewal, Higher Engineering Mathematics, 43<sup>rd</sup> Edition, Khanna Publishers.
- 2. N.P.Bali, Engineering Mathematics, Lakshmi Publications.

## **REFERENCE BOOKS:**

- 1. Erwin Kreyszig, Advanced Engineering Mathematics, 10<sup>th</sup> Edition, Wiley-India
- 2. Micheael Greenberg, Advanced Engineering Mathematics, 9<sup>th</sup> edition, Pearson edn
- 3. Dean G. Duffy, Advanced engineering mathematics with MATLAB, CRC Press
- 4. Peter O'neil, Advanced Engineering Mathematics, Cengage Learning.
- 5. Srimanta Pal, Subodh C.Bhunia, Engineering Mathematics, Oxford University Press.
- 6. Dass H.K., Rajnish Verma. Er., Higher Engineering Mathematics, S. Chand Co. Pvt. Ltd, Delhi.